

# Quadratic programming in synthesis of stationary Gaussian fields

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(joint work with V. Phipras and H. Helgason)

- 1 Synthesis of univariate processes using standard circulant embedding
- 2 Embedding methods for synthesis of 2D fields
- 3 Optimal circulant embedding

# Fast Fourier Transform (FFT)

Discrete Fourier Transform (DFT) of  $N$  complex numbers  $x_0, \dots, x_{N-1}$

$$X_k := \sum_{n=0}^{N-1} x_n e^{-i2\pi k \frac{n}{N}}, \quad k = 0, \dots, N-1. \quad (1)$$

- C.F.Gauss 1805, Joseph Fourier 1822, Cooley and Tukey 1965
- Direct calculation complexity is  $O(N^2)$
- Complexity of **FFT** is  $O(N \log N)$

*"The most important numerical algorithm of our lifetime"*

Gilbert Strang

# Some Linear Algebra

1	2	3	4
5	1	2	3
6	5	1	2
7	6	5	1

Toeplitz

1	2	3	4
4	1	2	3
3	4	1	2
2	3	4	1

Circulant

- Toeplitz: All diagonals remain constant
- Circulant: Each row is the preceding row shifted one entry to the right
- DFT basis diagonalizes circulant matrices. FFT can be used for efficient computation of the eigenvalues

# One dimensional case

Consider a zero mean **stationary Gaussian** time series  $\{X_n\}_{n \in \mathbb{Z}}$  with autocovariance function

$$r(n) = EX_0 X_n.$$

Question: How does one generate  $X := (X_0, \dots, X_{N-1})'$ , given the **autocovariance function** of  $X$ ?

Denote the covariance matrix of  $X$  by

$$\Sigma = EXX' = \begin{pmatrix} r(0) & r(1) & r(2) & \dots & r(N-1) \\ r(1) & r(0) & r(1) & \dots & r(N-2) \\ r(2) & r(1) & r(0) & \dots & r(N-3) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r(N-1) & r(N-2) & r(N-3) & \dots & r(0) \end{pmatrix}$$

Since  $\Sigma$  is non-negative definite, using Cholesky decomposition we can factorize

$$\Sigma = \Sigma^{1/2} \Sigma^{1/2}$$

and set

$$X = \Sigma^{1/2} Z$$

where  $Z$  is a  $N(0, I_N)$  vector.

Problem: The complexity of this method is  $O(N^3)$ , and the approach is practical only for moderate sample sizes  $N$ . What about larger  $N$ ?

# Univariate Standard Circulant Matrix Embedding (SCE)

A **Circulant Matrix Embedding** of  $\Sigma$  is a circulant matrix

$$\tilde{\Sigma} = \begin{pmatrix} r(0) & r(1) & \dots & r(N-1) & r(N-2) & \dots & r(1) \\ r(1) & r(0) & \dots & r(N-2) & r(N-1) & \dots & r(2) \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ r(N-1) & r(N-2) & \dots & r(0) & r(1) & \dots & r(N-2) \\ r(N-2) & r(N-1) & \dots & r(1) & r(0) & \dots & r(N-3) \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ r(1) & r(2) & \dots & r(N-2) & r(N-3) & \dots & r(0) \end{pmatrix}$$

of dimension  $M \times M$  with embedding size  $M = 2N - 2$ . Note that  $\tilde{\Sigma}$  contains the covariance matrix  $\Sigma$ . Let also

$$\tilde{r}(n) = (r(0), r(1), \dots, r(N-1), r(N-2), \dots, r(1)).$$

# Univariate SCE

The discrete Fourier basis diagonalizes circulant matrices:

$$\tilde{\Sigma} = F^* \Lambda F.$$

- $j$ th column of  $F^*$  is  $(1, e^{-i\frac{2\pi j}{M}}, \dots, e^{-i\frac{2\pi j(M-1)}{M}}) / \sqrt{M}$
- $\Lambda = \text{diag}(\lambda_0, \dots, \lambda_{M-1})$ , where the real eigenvalues of  $\tilde{\Sigma}$  are

$$\lambda_m = \sum_{j=0}^{M-1} \tilde{r}(j) e^{-i\frac{2\pi jm}{M}}$$

and can be computed rapidly using FFT (complexity  $O(M \log M)$ ).

**Condition ND:** The eigenvalues  $\lambda_m$ ,  $m = 0, \dots, M - 1$ , are **non-negative**.

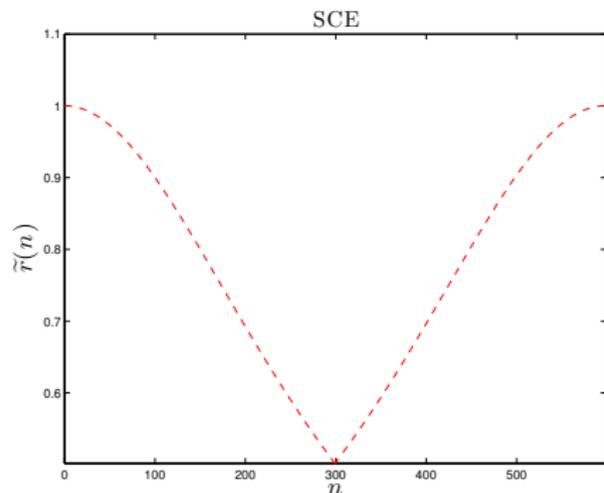
If ND holds then both

$$\tilde{X} = \mathcal{R}(F^* \Lambda^{1/2} Z), \quad \text{and} \quad \tilde{X} = \mathcal{I}(F^* \Lambda^{1/2} Z)$$

have covariance matrix  $\tilde{\Sigma}$ .

# On ND Condition

The circulant matrix embedding for the covariance structure below has 298 negative eigenvalues.



- ND holds if  $\{r(n)\}_{0 \leq n \leq N-1}$  satisfies
- convex, decreasing, nonnegative  
or
  - $r(k) \leq 0, k = 1, \dots, N-1$   
or
  - N is large enough

If  $\tilde{\Sigma}$  is not smooth at the boundary of periodization, ND is likely to fail

# Standard SCE for 2D fields

Consider a zero mean **stationary Gaussian** field  $\{X_n, n \in \mathbb{Z}^2\}$  with autocovariance function

$$r(n) = r(n_1, n_2) = EX_0 X_n, \quad n \in \mathbb{Z}^2.$$

**Goal:** Generate the field  $X$  on the **square grid**

$$G(N) = \{n \in \mathbb{Z}^2 : 0 \leq n_1, n_2 \leq N - 1\}.$$

given  $r(n)$  in  $\tilde{G}(N) = \{n \in \mathbb{Z}^2 : -N + 1 \leq n_1, n_2 \leq N - 1\}$

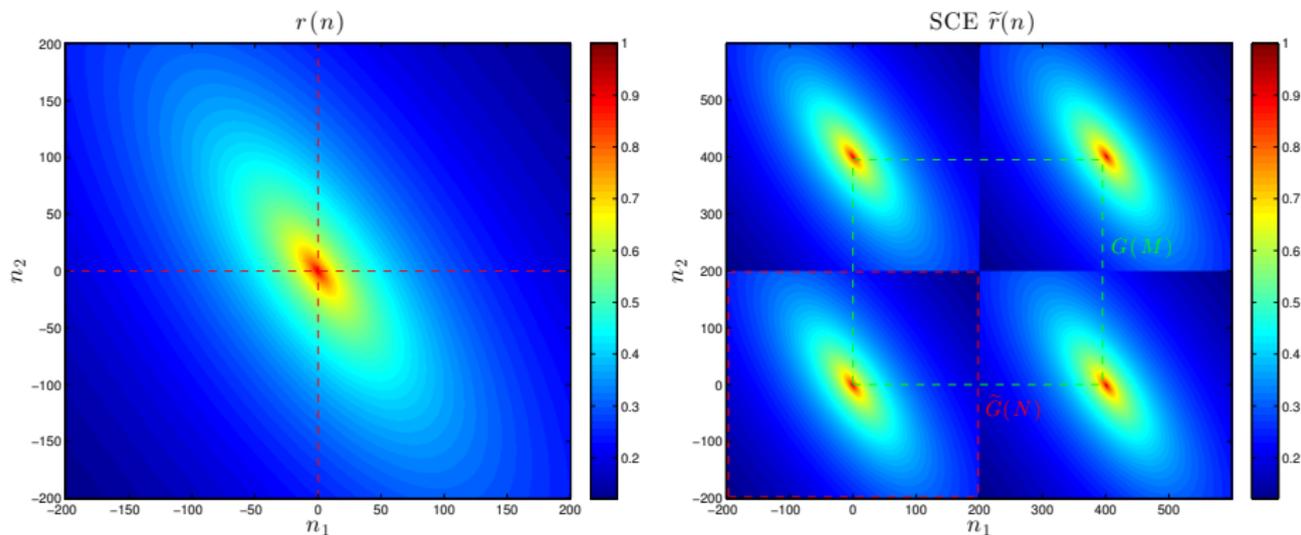
Question: What is the covariance embedding  $\tilde{r}(n)$ ?

Example: **Powered exponential covariance function**

$$r(n) = e^{-(0.01\|n\|_W)^{0.5}}, \quad \|t\|_W := \sqrt{t' W t}, \quad W = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix},$$

with  $N = 200$  and  $M = 2N - 1 = 399$ .

# Standard SCE for 2D fields



Extension scheme:  $\tilde{r}(n) = r(n)$ ,  $n \in \tilde{G}(N)$ , and  $M$ -periodic

# Standard SCE for 2D fields

The eigenvalues of the covariance embedding are given by the 2D DFT.

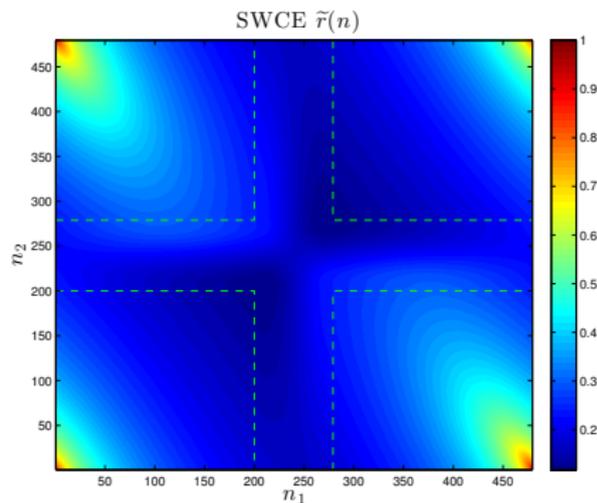
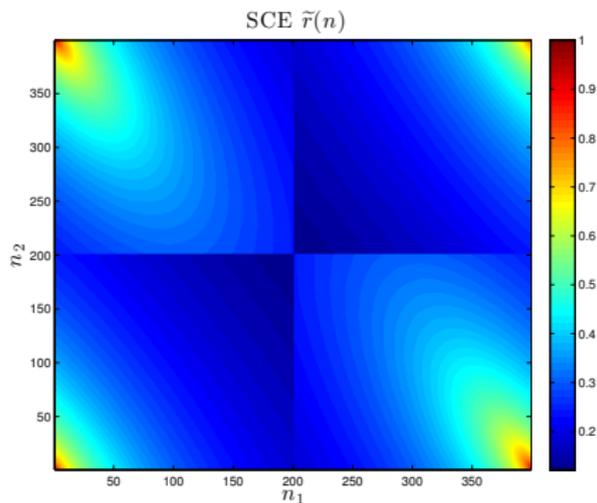
$$\lambda_k(\tilde{r}(n)) = \sum_{n \in G(M)} \tilde{r}(n) e^{-i2\pi k \cdot (n/M)}, \quad k \in G(M)$$

- If ND holds we can construct  $X$  as in the univariate case. Condition ND seems to fail quite often in 2D. **Embedding matrix not smooth at the boundary of periodization ?**

Solutions:

- ▶ Increase  $N$  to some  $\tilde{N}$  and take  $M = 2\tilde{N} - 1$ . It is convenient to think of  $\tilde{G}(\tilde{N}) \setminus \tilde{G}(N)$  as the transition region. Increasing  $N$  to  $\tilde{N}$  in SCE can be thought as extending  $r(n)$  over the transition region.
- ▶ **Smoothing Windows Circulant Embedding (SWCE).**
  - Apply a smoothing kernel over the transition region
  - Works well for several covariance structures.
  - Outperforms existing variants of SCE.

# SCE and SWCE



Left: SCE  $\tilde{r}(n)$  for  $N = 200$ ,  $M = 399$  with 56000 negative eigenvalues.

Right: SWCE  $\tilde{r}(n)$  for  $\tilde{N} = 240$ ,  $M = 479$  with 50 negative eigenvalues.

# Optimal Circulant Embedding

The covariance embedding  $\tilde{r}(n)$  needs to satisfy the following

- $\tilde{r}(n) = r(n)$  for  $n$  inside the dotted areas,  $\tilde{r}(n) = \tilde{r}(-n)$
- Nonnegative eigenvalues

Idea: Obtain a circulant matrix embedding as the solution of a quadratic optimization problem with linear inequality constraints

$$\begin{aligned} \min_{\tilde{r}(n)} \quad & f(\tilde{r}) = \sum_{n \in G(M)} w(n) (r(n) - \tilde{r}(n))^2, \\ \text{subject to} \quad & g_k(\tilde{r}) \geq 0, \quad k \in G(M) \end{aligned}$$

Remark: We only need to focus on the left sub-grid  $L$  of  $G(M)$ , both for the objective function and the constraints

$$\begin{aligned} \min_{\tilde{r}(n)} \quad & f(\tilde{r}) = \sum_{n \in L} w(n) (r(n) - \tilde{r}(n))^2, \\ \text{subject to} \quad & g_k(\tilde{r}) \geq 0, \quad k \in L. \end{aligned} \tag{C}$$

# Primal log-barrier method

- $\tilde{r}(n)$  feasible point:  $g_k(\tilde{r}(n)) \geq 0$ ,  $k \in L$
- optimal value of (C):  $z^* = \inf\{f(\tilde{r}) \mid g_k(\tilde{r}) \geq 0, k \in L\}$
- $\tilde{r}^*$  optimal point:  $\tilde{r}^*$  is feasible and  $f(\tilde{r}^*) = z^*$
- $\tilde{r}(n)$   $\epsilon$ -suboptimal point:  $\tilde{r}$  is feasible and  $f(\tilde{r}) - z^* \leq \epsilon$

## Part 1: Eliminate the constraints

$$\min_{\tilde{r}} f_t(\tilde{r}) := f(\tilde{r}) - \frac{1}{t} \sum_{k \in L} \log(g_k(\tilde{r})) \quad (\text{U})$$

Fact: The solutions of the unconstrained problems (U),  $\{\tilde{r}_t^*, t > 0\}$  (*central path points*) approach a solution of the constrained problem (C) as  $t$  grows. In fact they are at most  $m/t$ -suboptimal, i.e.

$$f(\tilde{r}_t^*) - z^* \leq m/t,$$

where  $m$  is the number of inequality constraints.

## Part 2: Quadratic approximation

For a given  $x = x_0$  and a fixed  $t$  consider the second-order Taylor approximation  $\widehat{f}_t$

$$\widehat{f}_t(x + v) = f_t(x) + \nabla f_t(x)v + \frac{1}{2}v^T \nabla^2 f_t(x)v$$

Calculate the direction  $v$  that minimizes  $\widehat{f}_t$  (*Newton step*)

$$\min_v \quad \nabla f_t(x)v + \frac{1}{2}v^T \nabla^2 f_t(x)v \quad (\text{N})$$

Fact 1: Multiple *Newton steps* yield a sequence of points  $x_k = x_{k-1} + v$  that converges to the minimizer of  $f_t$

Fact 2: We only need to take 1 Newton step!

# Primal log-barrier method

**Part 3: Conjugate gradient algorithm.** First order conditions of (N)

$$Hv = b, \quad H = \nabla^2 f_t(x), \quad b = -\nabla f_t$$

Given  $v_0$ ; Set  $\epsilon_0 = Hv_0 - b$ ,  $p_0 = \epsilon_0$ ,  $k = 0$ ;

**while**  $\epsilon_k \neq 0$

$$\alpha_k \leftarrow \frac{\epsilon_k^T \epsilon_k}{p_k^T H p_k};$$

$$v_{k+1} \leftarrow v_k + \alpha_k p_k;$$

$$\epsilon_{k+1} \leftarrow \epsilon_k + \alpha_k H p_k;$$

$$s_{k+1} \leftarrow \frac{\epsilon_{k+1}^T \epsilon_{k+1}}{\epsilon_k^T \epsilon_k};$$

$$p_{k+1} \leftarrow -\epsilon_{k+1} + s_{k+1} p_k;$$

$$k \leftarrow k + 1;$$

**end (while)**

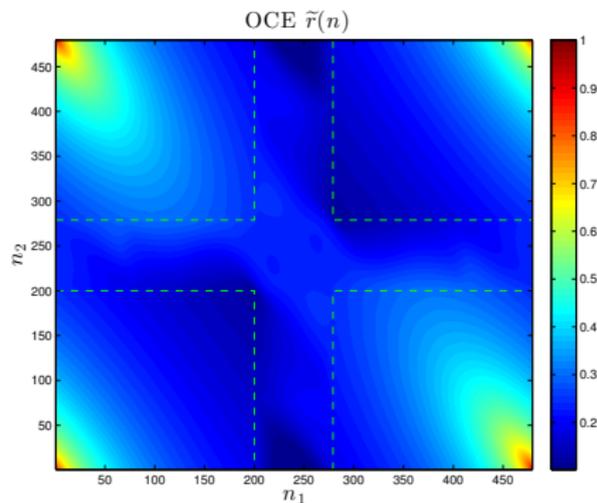
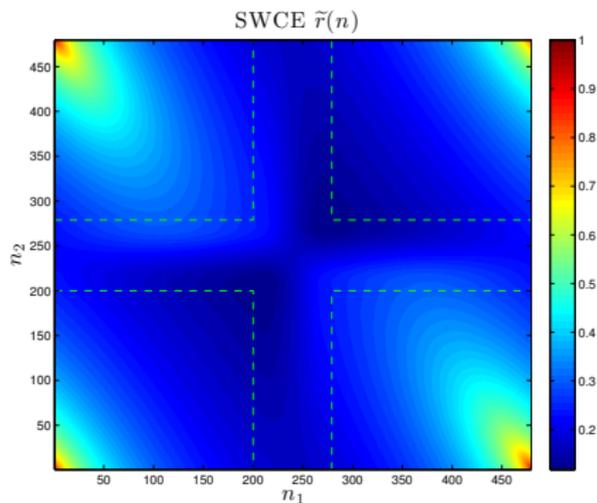
# Primal log-barrier method

- Direct computation  $Hp_k$  is of order  $O(N^4)$
- Using 2D FFT the order drops to  $O(N^2 \log N)$
- $\epsilon_k$  doesn't need to be taken very small

## Steps of the PLB method

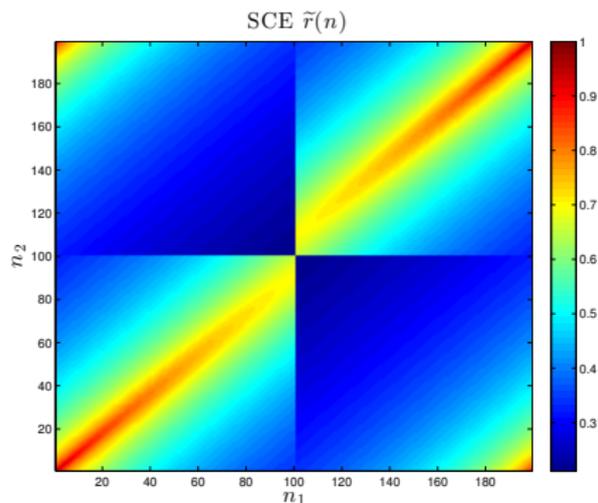
- 1 Find an initial strictly feasible point  $\tilde{r}$ . Pick  $\mu > 1$ ,  $t > 0$ ,  $\epsilon > 0$ .
- 2 Compute  $\tilde{r}_{t,a}^*$  by solving (N) with initial point  $\tilde{r}$ .
- 3 Update  $\tilde{r} = \tilde{r}_{t,a}^*$ . If  $m/t < \epsilon$ , stop and return  $\tilde{r}$ .
- 4 Increase  $t$  to  $\mu t$  and start again from Step 2.

# SWCE and OCE



Left: SWCE  $\tilde{r}(n)$  for  $N = 200$ ,  $\tilde{N} = 240$ ,  $M = 479$  with 50 negative eigenvalues.  
Right: OCE  $\tilde{r}(n)$  with no negative eigenvalues and objective function value  $10^{-7}$ .

The magnitude of the eigenvalues of  $W$  affect the smoothness of the embedding



18000 negative eigenvalues

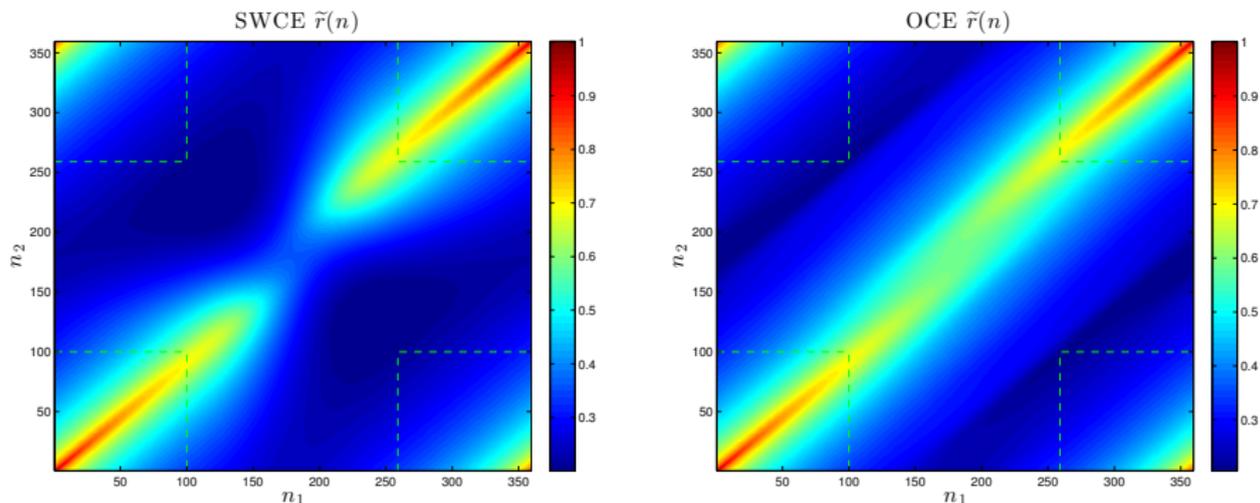
Powered exponential covariance with near singular  $W$

$$r(n) = e^{-(0.01\|n\|_W)^{0.5}}$$

$$W = \begin{pmatrix} 1.6 & -1.5 \\ -1.5 & 1.4 \end{pmatrix}$$

$$\lambda_W = (0.01, 3)$$

# SWCE and OCE



Left: SWCE  $\tilde{r}(n)$  for  $N = 100$ ,  $M = 359$  with 116 negative eigenvalues.

Right: OCE  $\tilde{r}(n)$  with no negative eigenvalues and objective function value  $10^{-6}$ .

- OCE and SWCE for intrinsic Gaussian random fields
- Preconditioning in conjugate gradient algorithm
- Alternative measures - KL divergence ?
- Primal-dual path following algorithm

- Fast and exact simulation of stationary Gaussian processes through circulant embedding of the covariance matrix (Dietrich and Newsam), *SIAM J. Sci. Comput.*, 1997.
- Simulation of stationary Gaussian vector fields. (Chan and Wood), *Statistics and Computing*, 1999.
- Smoothing windows for the synthesis of Gaussian stationary random fields using circulant matrix embedding. (Helgason, Pipiras and Abry), *J. of Comput. and Graph. Stats.*, 2014.
- Convex optimization and feasible circulant matrix embeddings in synthesis of stationary Gaussian fields. (Helgason, Kechagias, Pipiras), *Preprint*.

**Thank you!**

**Question 1:** Does the OCE method work for any covariance structure?

- As with other embedding methods, OCE's performance depends on the **strength of discontinuities** of the covariance embedding
- Large  $\mu$  is more likely to lead to an exact embedding, which however might have some negative eigenvalues.
- Small  $\mu$  ensures the eigenvalues will be nonnegative, however leading to approximate embeddings.

**Question 2:** How does the OCE method compares with Cholesky and SWCE in terms of speed?

- For  $N > 100$  Cholesky breaks down (complexity  $O(N^5)$ )
- SWCE is faster at first glance. However the minimum transition region length needed is not known in advance.